Stroke Reading Cylinder and Counter

CE Series



Air Cylinder with Measurement Function/Stroke Reading Cylinder CE series

Counter CEU Series

Measurement is possible throughout the full stroke range.

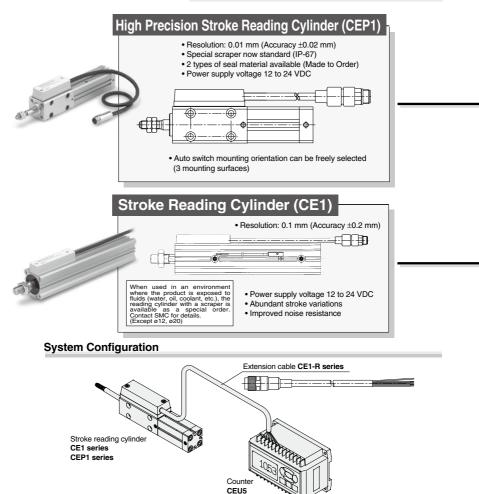
within the cylinder stroke.

the cylinder rod to the reference plane, that point becomes the home position.

Can be used in an environment where the product is exposed to fluids (water, oil, coolant, etc.)

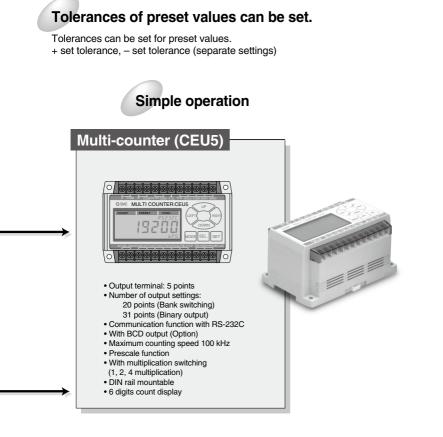
CEP1 Series With special scraper as standard CE1 Series Special order (with scraper) *

* The standard type of the CE1 series does not come with a scraper. Contact SMC since cylinders with a scraper are special orders.



@SMC

Achieve rationalization of production lines Stroke reading cylinder with position feedback



CEP1 CE1 CE2 ML2B

Series Variations

CE1	Series

Bore size	Standard stroke (mm)												Manufacturable
(mm)	25	50	75	100	125	150	175	200	250	300	400	500	stroke range
12	•	٠	•	•	•	•							25 to 150
20	•	۲	•	•	•	•	٠	•					25 to 300
32		۲	٠	•	•	•	٠	•	•	•			25 to 400
40				•	•	•	•	•	•	•	•	•	25 to 600
50								•		•		•	25 to 600
63								•		•		•	25 to 600

CEU5

Count data output	RS-232	C+BCD	RS-232C				
Output transistor mode	NPN	PNP	NPN	PNP			
100 to 240 VAC	۲	۲	٠	•			
24 VDC	۲	۲	۲	•			

Extension Cable

@SMC

CEP1 Series

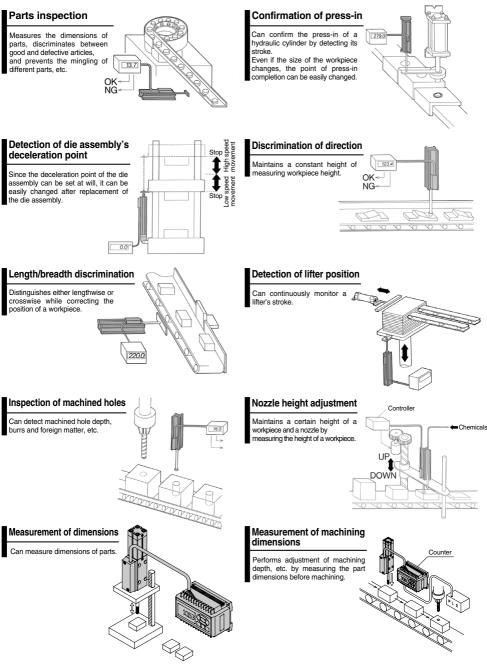
Bore size	Stand	dard s	troke	(mm)	Manufacturable
(mm)	25	50	75	100	stroke range
12 equivalent	•	•	•	•	1 to 150
20 equivalent	•	•	•	•	1 to 300

 Strokes other than standard strokes are available upon request. Consult with SMC separately.



CE Series

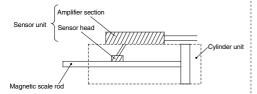
Application Examples



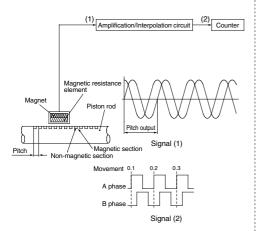
SMC

Measurement Principle

The amount of rod movement in the stroke reading cylinder is detected using an MR element (magnetic resistance element) whose resistance value changes due to magnetic force. The detection unit containing this MR element is called the sensor head. An amplifying circuit and a dividing circuit are required to produce output which can be read by the counter, and these are attached to the cylinder case. The sensor head and amplifier section together are referred to as the sensor unit.



The stroke reading cylinder is equipped with the capability of outputting the piston stroke movement as a pulse signal. The measurement principle is as shown in the drawing below.



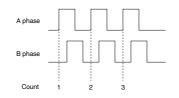
- Scales of magnetic layers and non-magnetic layers are etched at a certain pitch on the piston rod.
- With movement of the piston rod, a sin, cos 2-phase signal (Signal (1)) is received by the magnetic resistance element. For this wave form, 1 pitch (0.8 mm) becomes exactly 1 cycle.
- 3. This is amplified and divided into 1/8 parts. As a result, a 90° phase difference pulse signal of 0.1 mm/pulse (Signal (2)) is output.
- By measuring this pulse signal with the counter, it is possible to detect the piston position with a resolution of 0.1 mm.
- 5. In the case of the high precision stroke reading cylinder, the sin, cos 2-phase signal obtained in 2 is amplified and divided into 1/20 parts. As a result, a 90° phase difference pulse signal of 0.04 mm/pulse (Signal (2)) is output.
- 6. By multiplying this pulse signal by 4 with the counter, it is possible to detect the piston position with a resolution of 0.01 mm.

A/B Phase Difference Output (90° phase difference output)

When movement is expressed by a single line of pulses, it is impossible to accurately identify the current position, because pulse waves appear in both upward and downward directions.

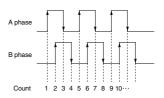
Accordingly, in A/B phase difference output, two lines of pulses are provided, wherein one line detects the movement and the other distinguishes the direction.

The CE1 also employs this system.



4 Times Multiplication Function

This function increases resolution 4 times by counting 4 for each cycle of pulses, instead of counting 1 for each cycle as is normally the case. In principle, this function counts each time there is a rise or fall in either of the A or B phase pulses.



Counting Speed (kHz, kcps)

Counting speed indicates the number of pulses that can be counted per second. If the stroke reading cylinder is operated at high speeds, pulse waves are output in shorter cycles. The counting speed of the counter must be higher than the pulse speed for the maximum piston speed when operating. Since the stroke reading cylinder outputs one pulse for each 0.1 mm of movement, 5,000 pulses will be output for each 500 mm of movement. Therefore, a speed of 500 mm/s is equivalent to 5 kcps (kHz), but a counting speed 2 to 3 times greater is recommended for actual operation.

Accuracy

The accuracy is the difference between the dimensions based upon the signals of the stroke reading cylinder and the absolute dimensions.

The maximum display error that will appear on the counter's digital display is equal to twice (± 1 count) the resolution when the home position is reset and when dimensions are measured.





CE Series Specific Product Precautions

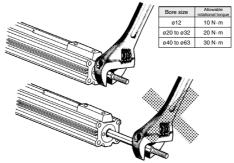
Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

A Caution

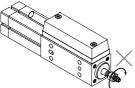
Mounting

1. When screwing a nut or fitting, etc. onto the threaded section at the end of the piston rod, return the piston rod to its fully retracted position, and grasp the exposed portion of the rod across two parallel sides with a wrench. In the case of the high precision stroke reading cylinder, there are no parallel sides. Secure the workpiece with a double nut.

Note) Do not apply rotational torque to the piston rod



- 2. Operate the cylinder in such a way that the load is always applied in the axial direction.
 - . In case the load is applied in a direction other than the axial direction of the cylinder, provide a guide to constrain the load itself.
- . When mounting a cylinder, centering should be done carefully.
- 3. Avoid using the air cylinder in such a way that rotational torque would be applied to the piston rod.



4. Be careful to avoid scratches or dents, etc. on the sliding sections of the piston rod.

Sensor Unit

- 1. The sensor unit is adjusted to an appropriate position at the time of shipment. Therefore, never detach the sensor unit from the body.
- 2. The cylinder should be protected from contact with liquids such as coolants or coolant water. Do not use in an environment where the unit is exposed to fluids. (CE1, CE2, ML2)
- 3. The sensor cable should not be pulled with a strong force.
- 4. Since the sensor for stroke reading cylinder adopts the magnetic method, it may result in malfunction if there is a strong magnetic field around the sensor. Use it under the external magnetic field with 14.5 mT or less.

This is equivalent to a magnetic field of approximately 18 cm in radius from a welding area using a welding amperage of almost 15,000 amperes. To use the system in a magnetic field that exceeds this value, use a magnetic material to shield the sensor unit.

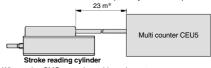
5. Switches or relays, etc. should not be installed in the power supply line (12 to 24 VDC).

▲ Caution

Effects of Noise

When the stroke reading cylinder is used near a motor, welding machine or other source of noise generation, there is a possibility of miscounting. In this case, noise should be suppressed as much as possible and the following countermeasure should be taken.

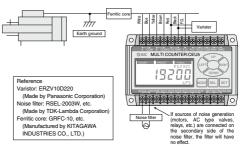
- 1. Connect the shield wire to FG (flame ground).
- 2. The maximum transmission distance for the stroke reading cylinder is 23 m, but since the output signal is a pulse output, the sensor cable should be wired separately from other power lines.



*When using SMC extension cable and counter.

Noise Counter Measures

- Methods of dealing with noise are given below
- 1. Connect only the shield wire to FG (frame ground).
- 2. Use a power source separate from large motors and AC valves, etc
- 3. Run the stroke reading cylinder's cable away from other power lines
- 4. Install a noise filter in the 100 VAC power line, a varistor in the DC power supply of the sensor cable and a ferritic core in the signal line (sensor cable).



<Counting speed of counter>

When the speed of the stroke reading cylinder is greater than the counting speed of the counter, the counter will miscount.

For CE1 (when measuring to 0.1 mm), a counter should be used with a counting speed of 10 kHz (kcps) or more.

And for CEP1 (when measuring to 0.01 mm), use a counter with a counting speed of 50 kHz (kcps) or more when 4 times multiplication is input.

<Malfunction due to lurching and bounding>

When lurching or bounding occurs at the beginning or end of stroke reading cylinder, or due to other causes, the cylinder speed momentarily increases, and there is a possibility of exceeding the counting speed of the counter or the response speed of the sensor, thereby causing a miscount.

Handling of Technical Material

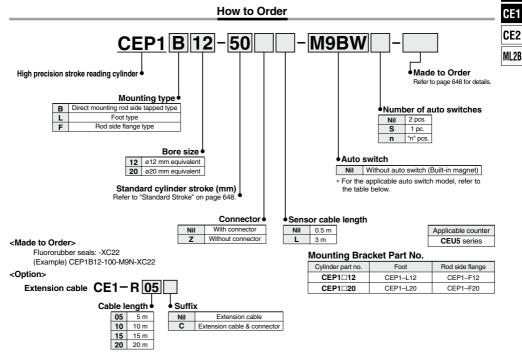
The operation manuals should be read before using the CEP1 series high precision stroke reading cylinder, CEU5 multi counter, CE1 scale cylinder and CEU1 3 point preset counter.





Refer to the multi-counter operation manual for details

CEP1



Applicable Auto Switches/Refer to pages 941 to 1067 for further information on auto switches.

		Electrical	ight	AND ST.	Lo	oad volta	ige	Auto swit	ch model	Lead wi	re le	ngth	(m)	Dro wirod									
Туре	Special function	entry	Indicator light	Wiring (Output)	D	С	AC	Perpendicular	In-line	0.5 (Nil)		3 (L)	5 (Z)	connector	Applical	ble load							
<u>-</u>				3-wire (NPN)	vire (NPN)		5 V. 12 V			M9NV	M9N	•	٠	•	0	0	IC circuit						
switch				3-wire (PNP)		5 V, 12 V		M9PV	M9P	•	٠	•	0	0	IC circuit								
s				2-wire	3-wire (NPN) 3-wire (PNP) 2-wire 3-wire (NPN)	12 V]	M9BV	M9B	•	•	•	0	0	-								
auto	Diagnostic indication	1		3-wire (NPN)							5 V. 12 V	V 10 V	M9NWV	M9NW	•	٠	•	0	0		Relay,		
	Diagnostic indication (2-color indicator) Grommet	Grommet	es	3-wire (PNP)		5 V, 12 V	'I — I	M9PWV	M9PW	•	•	•	0	0		PLC							
state			≻	2-wire									12 V	1	M9BWV	M9BW	•	٠	•	0	0	—	1.50
	Mater an eleterat	1		3-wire (NPN)				5 V. 12 V	1	M9NAV*1	M9NA*1	0	0	•	0	0	IC circuit						
Solid	Water resistant (2-color indicator)			3-wire (PNP)											5 V, 12 V		M9PAV*1	M9PA*1	0	0	•	0	0
ŭ				2-wire		12 V	1	M9BAV*1	M9BA*1	0	0	•	0	0	—								
Reed auto switch		Crommet	es	3-wire (NPN equivalent)	—	5 V	-	A96V	A96	•	—	•	—	-	IC circuit	—							
laut	Grommet Grommet				Grommet		2-wire	24 V	12 V	100 V	A93V*2	A93	•	٠	•	٠	-	—	Relay,				
Ree			R	2-wire	24 V	12 V	100 V or less	A90V	A90	•	-	•	-	-	IC circuit	PLC							

*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance

Consult with SMC regarding water resistant types with the above model numbers.

*2.1 m type lead wire is only applicable to D-A93.

* Lead wire length symbols: 0.5 m Nil (Example) M9NW

- 1 m M (Example) M9NWM 3 m I
 - (Example) M9NWL
 - (Example) M9NWZ 5 m Z

* Refer to page 655 for details on other applicable auto switches than listed above

* For details about auto switches with pre-wired connector, refer to pages 1014 and 1015.

* Auto switches are shipped together (not assembled).



* Solid state auto switches marked with "O" are produced upon receipt of order.

D-🗆
-X□

CEP1 Series



Cylinder Specifications

Action	Double acting, Single rod (Non-rotating piston)							
Fluid	Air							
Proof pressure	1.5 MPa							
Maximum operating pressure	1.0 MPa							
Minimum operating pressure	ø12 ø20							
minimum operating pressure	0.15 MPa 0.1 MPa							
Piston speed	50 to 300 mm/s							
Ambient and fluid temperature	0 to 60°C (No freezing)							
Lubrication	Non-lube							
Stroke length tolerance range	0 to +1.0 mm							
Cushion	Wit	nout						
Rod non-rotating accuracy	ø12	ø20						
nou non rotating accuracy	±2°	±3°						
Mounting	Direct mounting rod side tapped type (St	andard), Foot type, Rod side flange type						

Symbol



Made to	Made to Order Specifications
Order	Click here for details

Symbol	Specifications
-XC22	Fluororubber seals

Sensor Specifications

Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat & Flame resistant)
Maximum transmission distance	23 m (when using SMC cable and counter)
Position detection method	Magnetic scale rod, sensor head <incremental type=""></incremental>
Magnetic field resistance	14.5 mT
Power supply	10.8 to 26.4 VDC (Power supply ripple: 1% or less)
Current consumption	50 mA
Resolution	0.01 mm (With 4 times multiplication)
Accuracy	±0.02 mm ⁽¹⁾ (at 20°C)
Output type	Open collector (24 VDC, 40 mA)
Output signal	A/B phase difference output
Insulation resistance	500 VDC, 50 M Ω or more (between case and 12E)
Vibration resistance	33.3 Hz 6.8 G 2 hrs. each in X, Y directions 4 hrs. in Z direction based upon JIS D 1601
Impact resistance	30 G 3 times each in X, Y, Z directions
Enclosure	IP-67 (IEC Standard) ⁽²⁾
Extension Cable (Option)	CE1-R* 5 m, 10 m, 15 m, 20 m
take 4) This is should a deal distant a	

Note 1) This includes the digital display error of the counter (CEU5).

When strokes are over 100 mm, accuracy is ±0.05 mm.

Moreover, the overall accuracy after mounting on equipment will vary depending on mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole.

Note 2) Except for the connector, the cylinder section is the equivalent of an SMC water resistant cylinder.

Cylinder Stroke

		Manufacturable			
Model	25	50	75	100	stroke range
CEP1B12	•	•	•	•	1 to 150
CEP1B20	•	•	•	•	1 to 300

* Strokes other than standard strokes are available upon request for special. Consult with SMC separately.

Weight (Sensor cable length 0.5 m, With connector, Without mounting bracket (both ends tapped))

				(Kg)					
Bore size	Cylinder stroke (mm)								
(mm)	(mm) 25		75	100					
12	0.36	0.4	0.44	0.48					
20	0.56	0.62	0.68	0.74					

Note) For the type with a sensor cable length of 0.5m and without connector (CETICH-C2), 40g is subtraded from the weight shown above. For the type with a sensor cable length of 3m and connector (CETICH-C2), add 160g to the weight shown above. For the type with a sensor cable length of 3m and without connector (CETICH-C2), add 120g to the weight shown above.

(kg)

Mounting Bracket

	12	20
Rod side flange (F)	0.045	0.1
Foot (L)	0.035	0.045

Note 1) Including mounting bolt.

Note 2) The foot shows the weight for one set (2 pcs.).

Rod End Nut Dimensions

(2 pcs. are attached as standard.)



Material ø12, 20: Steel

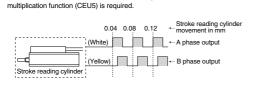
						(mm)
Part no.	Applicable bore size (mm)	d	н	в	С	D
DA00032	12	M5 x 0.8	3	8	9.2	7.8
DA00040	20	M8 x 1.25	5	13	15.0	12.5

Electrical Wiring

Output type

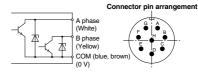
The output signal of the high precision stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below. The relation between the movement distance and the signal output of the high precision stroke reading cylinder is that for each 0.04 mm of movement a one pulse signal is output to both output terminals A and B. In order to

measure with a discrimination of 0.01 mm, a counter with a 4 times



Input/Output

The input/output of the stroke reading cylinder is performed by a ø7 shielded twisted pair wire from the sensor section plus a connector.



Output circuit of stroke reading cylinder

Signal

<u></u>						
Contact signal	Wire color	Signal name				
A	White	A phase				
В	Yellow	B phase				
С	Brown	COM (0 V) COM (0 V)				
D	Blue					
E	Red	+12 to 24 V				
F	Black	0 V				
G	_	Shield				

D-🗆
-X□

Auto Switch Proper Mounting Position

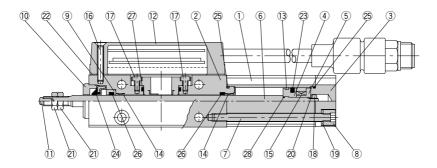
Regarding dimensions for the auto switch proper mounting position (at stroke end), refer to page 655.

CEP	1
CE1	
CE2	2
ML2E	}

CEP1 Series

Construction

ø12, ø20



Component Parts

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Rod cover	Aluminum alloy	Hard chrome plated
3	Head cover	Aluminum alloy	Hard anodized
4	Piston A	Aluminum alloy	Hard anodized
5	Piston B	Aluminum alloy	Hard anodized
6	Piston rod	Carbon steel	Hard chrome plated
7	Tie-rod	Carbon steel	Chromated
8	Tie-rod nut	Carbon steel	Chromated
9	Seal ring	Aluminum alloy	White anodized
10	Centering location ring	Aluminum alloy	White anodized
11	Rod end pin	Stainless steel	Quenched
12	Sensor unit	_	With or without connector
13	Wear ring	Special resin	
14	Bushing	Cast iron	

Component Parts

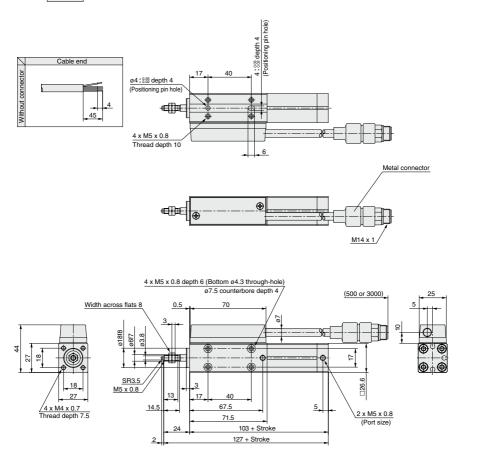
		NL L
Description	Material	Note
Magnet	-	
Cross recessed countersunk head screw	Chromium molybdenum steel	Chromated
Hexagon socket head cap screw	Stainless steel	
Hexagon nut	Carbon steel	Chromated
Spring washer	Steel wire	Chromated
Spring washer	Steel wire	Chromated
Hexagon nut	Carbon steel	Rod end nut
Sensor case gasket	NBR	
Piston seal	NBR	
Scraper	NBR	
Tube gasket	NBR	
Rod seal	NBR	
O-ring	NBR	
O-ring	NBR	
	Cross recessed countersunk head screw Hexagon socket head cap screw Hexagon nut Spring washer Spring washer Hexagon nut Sensor case gasket Piston seal Scraper Tube gasket Rod seal O-ring	Magnet — Cross recessed countersunk head screw Chronium molybdenum steel Hexagon socket head cap screw Stainless steel Hexagon nut Carbon steel Spring washer Steel wire Hexagon nut Carbon steel Spring washer Steel wire Hexagon nut Carbon steel Sensor case gasket NBR Piston seal NBR Scraper NBR Rod seal NBR O-ring NBR

* Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

Dimensions: ø12

Direct mounting, rod side tapped type:

CEP1B12 - Stroke



651

CEP1 CE1

CE2

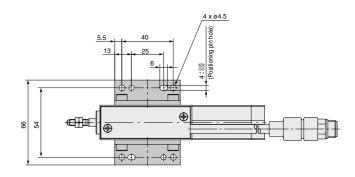
ML2B

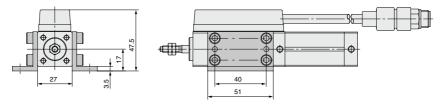
CEP1 Series

Dimensions: ø12

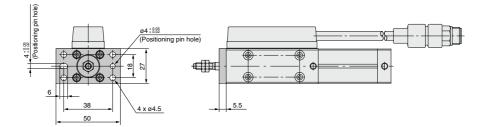
Foot type:

CEP1L12 - Stroke





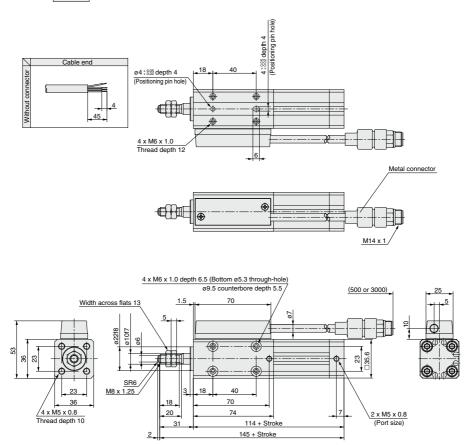
Rod side flange type: CEP1F12 - Stroke



Dimensions: ø20

Direct mounting, rod side tapped type:

CEP1B20 - Stroke





CEP1 CE1

CE2

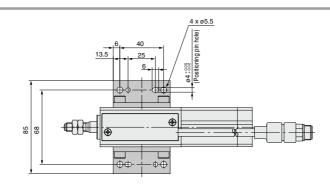
ML2B

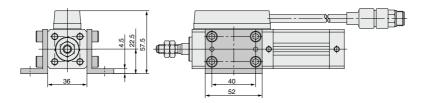
CEP1 Series

Dimensions: ø20

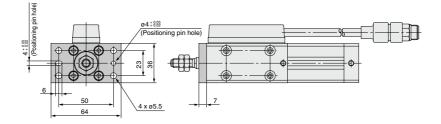
Foot type:

CEP1L20 - Stroke



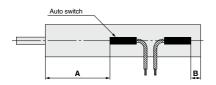


Rod side flange type: CEP1F20 - Stroke



CEP1 Series Auto Switch Mounting

Auto Switch Proper Mounting Position (Detection at Stroke End)



Auto Switch Proper Mounting Position (mm)

Auto switch model	D-A D-A		D-M9 D-M9 D-M9 D-M9 D-M9 D-M9	□V □W □WV □A		
Bore size \	Α	В	Α	в		
12	75	8	79	12		
20	82	12	86	16		

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Operating Range

		(mm)	
	Bore	size	
Auto switch model	12	20	GEPT
D-A9□/A9□V	6	10	0.54
D-M9□/M9□V			CE1
D-M9□W/M9□WV D-M9□A/M9□AV	3	4	CE2

ML2B

 Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.

Other than the	models listed in "How to Order", the following auto switches are applicable. auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1014 and 1015
	d (NC = b contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 959.

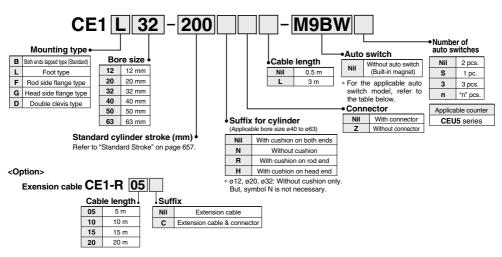


Stroke Reading Cylinder **CE1** Series Ø12, Ø20, Ø32, Ø40, Ø50, Ø63

Note) CE-compliant: When connecting to a multi-counter (CEU5CID-D, power supply voltage 24 VDC). Refer to the counter operation manual for details.



How to Order



Applicable Auto Switches/Refer to pages 941 to 1067 for further information on auto switches.

		Electrical	light	147.1	Ĺ	oad vol	tage	Auto swit	tch model	Lea	d wir	re ler	ngth	(m)	Pre-wired							
Туре	Special function	entry	Indicator light	Wiring (Output)	D	с	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)		None (N)	connector	Applica	ble load					
				3-wire (NPN)		5 V,		M9NV	M9N	۲	٠	•	0	—	0	IC circuit						
switch	Gromm	Grommet		3-wire (PNP)		12 V		M9PV	M9P	٠	۲	٠	0	—	0	IC CITCUIT						
ž				2-wire		12 V		M9BV	M9B	۲	۲	۰	0	—	0							
1S O		Connector				12 V		J79C	—	٠	—	۰	•	٠	—							
auto	Diagnostic indication			3-wire (NPN)	24 V	5 V,		M9NWV	M9NW	٠	٠	۰	0	—	0	IC circuit	Relay,					
ea	(2-color indicator)		res	3-wire (PNP)		24 V	24 V	12 V	_	M9PWV	M9PW	٠	۲	۰	0	-	0		PLC			
state		a L		2-wire	ſ [12 V	12				M9BWV	M9BW	•	•	•	\circ	-	0	-
			3-wire (NPN)	12 V	5 V,	M9NAV*1	M9NA*1	0	\circ	•	0	—	0	IC circuit								
Solid	(2-color indicator)		3-wire (PNP)			M9PAV*1	M9PA*1	0	\circ	•	0	-	0	10 circuit								
۰Ö	. ,			2-wire					12 V		M9BAV*1	M9BA*1	0	$^{\circ}$	۰	\circ	-	0	—			
	With diagnostic output (2-color indicator)			4-wire		5 V, 12 V			F79F	٠	—	•	0	—	0	IC circuit						
switch			6	3-wire (NPN equivalent)	_	5 V	—	A96V	A96	٠	_	•		-	_	IC circuit	_					
Ň		Grommet	Yes		1	—	200 V	A72	A72H	٠	—	٠	-	—	—							
ő						12 V	100 V	A93V*2	A93	٠	•	•	•	-	-							
aut	auto		٩	2-wire		5 V, 12 V	100 V or less	A90V	A90	۲	—	•	-	_	-	IC circuit	Relay,					
D		Connector	Yes	2-44116	24 V	12 V	_	A73C	—	٠	—	•	٠	•	—	-	PLC					
Reed		CONTRECIO	R	1		5 V, 12 V	24 V or less	A80C	—	۲	—	•	•	•	-	IC circuit						
	Diagnostic indication (2-color indicator)	Grommet	Yes			—	—	A79W	_	۲	-	٠	-	-	-	Ì						

*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.

Consult with SMC regarding water resistant types with the above model numbers.

*2 1 m type lead wire is only applicable to D-A93

* Lead wire length symbols: 0.5 mNil

 .5 m
Nil
 (Example) M9NW

 1 m
 (Example) M9NWM
 3 m
 (Example) M9NWL

 3 m
 (Example) M9NWL
 (Example) M9NWL

 5 m
 Z
 (Example) M9NWZ

* Refer to page 666 for details on other applicable auto switches than listed above

* For details about auto switches with pre-wired connector, refer to pages 1014 and 1015.

When D-A9□(V)/M9□(V)/M9□W(V)/M9□A(V)L types with ø32 to ø63 are mounted on a side other than the port side, order auto switch mounting brackets. separately. Refer to page 666 for details.

* Solid state auto switches marked with "O" are produced upon receipt of order.

* Auto switches are shipped together (not assembled).

Nor



Cylinder Specifications



Fluid		A	ir								
Proof pressure		1.5	MPa								
Maximum operating pressure		1.0	MPa								
Minimum operating pressure	ø12		ø20 to ø63								
winning pressure	0.07 MPa			0.05 MPa							
Piston speed		70 to 50	00 mm/s								
Ambient and fluid temperature	0 to 60°C (No freezing)										
Humidity	25 to 85% RH (No condensation)										
Lubrication		Non-	lube								
Stroke length tolerance range	ø12, ø20: *	1.0 0	ø32, ø	ø40, ø50, ø63: +1.6 0							
With Air cushion	ø12, ø20, ø32····	None	ø40,	ø50, ø63····With							
Rod non-rotating accuracy	ø12	øź	20	ø32, ø40, ø50, ø63							
nou non-rotating accuracy	±2°	±.	1°	±0.8°							
Mounting	Both ends tapped type (Standard), Foot type, Flange type, Double clevis type										
Auto switch	Re	ed type, So	olid state ty	ре							

Symbol



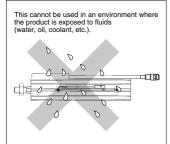
Mounting Bracket Part No.

Bore size (mm)	Foot Note 1)	Flange	Double clevis
12	CQ-L012	CQ-F012	CQ-D012
20	CQ-L020	CQ-F020	CQ-D020
32	CQ-L032	CQ-F032	CQ-D032
40	CQ-L040	CQ-F040	CQ-D040
50	CQ-L050	CQ-F050	CQ-D050
63	CQ-L063	CQ-F063	CQ-D063

Note 1) When ordering the foot bracket, order 2 pcs. per cylinder. Note 2) Parts belonging to each bracket are as

Note 2) Parts belonging to each bracket are as follows.

Foot, Flange/Body mounting bolts Double clevis/Clevis pin, type C retaining ring for shaft, Body mounting bolts



The reading cylinder with a scraper is available as a special order. Contact SMC for details. (ø32 to ø63) For ø12 and ø 20 models, use the CEP1 series

with the scraper provided as standard accessory.

Sensor Specifications

Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat & Flame resistant cable)									
Maximum transmission distance	23 m (when using SI	MC cable and counter)								
Position detection method	Magnetic scale rod <non-rotating></non-rotating>	Sensor head <incremental type=""></incremental>								
Magnetic field resistance	14.5 mT									
Power supply	10.8 to 26.4 DC (Power	supply ripple: 1% or less)								
Current consumption	40	mA								
Resolution	0.1 mm/pulse									
Accuracy	±0.2 mm	(at 20°C) (1)								
Output type	Open collector	(24 VDC, 40 mA)								
Output signal	A/B phase di	fference output								
Insulation resistance	50 M Ω or more (500 VDC measured via	a megohmmeter) (between case and 12E)								
Vibration resistance		, Y directions 4 hrs. in Z direction n JIS D 1601								
Impact resistance	30 G 3 times each	in X, Y, Z directions								
Enclosure	IP65 (IEC Standard) (2	2) Except connector part								
Extension cable (Option)	5 m, 10 m,	15 m, 20 m								

Note 1) This includes the digital display error of the counter (CEU5).

Moreover, the overall accuracy after mounting on equipment will vary depending on the mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole. Note 2) The cylinder section does not have a water resistant enclosure.

Cylinder Stroke

Bore size		Manufacturable											
(mm)	25	50	75	100	125	150	175	200 250		300	400	500	stroke range
12	٠	•	٠	•	٠	•	-	-	—	—	—	-	25 to 150
20	٠	•	٠	•	•	•	٠	٠	-	-	-	-	25 to 300
32	—	•	٠	•	٠	٠	٠	٠	٠	٠	-	-	25 to 400
40	—	—	—	•	٠	•	٠	٠	•	٠	•	٠	25 to 600
50	-	-	_	—	-	-	_	•	-	٠	—	٠	25 to 600
63	—	—	—	_	-	—	—	٠	_	٠	—	٠	25 to 600

Strokes other than standard strokes are available upon request for special. Consult with SMC separately.

Especially, be careful of an eccentric load applied to the rod when the stroke is over 100 mm with a bore size of 12 mm.

D-🗆

-X 🗆

Weight (Sensor cable length 0.5 m, With connector, Without mounting bracket (both ends tapped))

												(kg)				
Bore size		Cylinder stroke (mm)														
(mm)	25	50	75	100	125	150	175	200	250	300	400	500				
12	0.28	0.32	0.35	0.39	0.42	0.46	—	—	—	—	-	—				
20	0.48	0.55	0.62	0.69	0.76	0.83	0.9	0.97	-	-	-	-				
32	-	0.84	0.95	1.05	1.16	1.26	1.37	1.48	1.69	1.9	_	—				
40	-	_	_	1.58	1.71	1.83	1.96	2.08	2.33	2.58	3.08	3.58				
50	-	_	_	_	_	_	_	3.26	_	3.96	_	5.36				
63	_	_	_	_	_	_	_	4.04	_	4.84	_	6.44				

Note 1) For the type with a sensor cable length of 0.5m and without connector (CE1□□-□Z), 40g is subtracted from the weight shown above.

For the type with a sensor cable length of 3m and connector (CE1□□-□L), add 160g to the weight shown above.

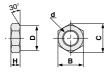
For the type with a sensor cable length of 3m and without connector (CE1□□-□ZL), add 120g to the weight shown above.

Note 2) The mounting bracket weight is shared with the compact cylinder (CQ2 series). So, refer to the CQ2 series catalog.

Rod End Nut Dimensions

(1 pc. is attached as standard.)

Material ø12, 20: Steel ø32 to ø63: Rolled steel



							(mm)
,	Part no.	Applicable bore size (mm)	d	н	в	с	D
-	NTJ-015A	12	M5 x 0.8	4	8	9.2	7.8
	NT-02	20	M8 x 1.25	5	13	15.0	12.5
	NT-04	32 · 40	M14 x 1.5	8	22	25.4	21.0
	NT-05	50·63	M18 x 1.5	11	27	31.2	26

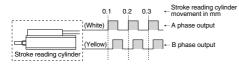
Electrical Wiring

Output type

The output signal of the stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below.

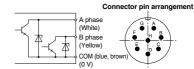
The relation between the movement distance and the signal output of the stroke reading cylinder is that for each 0.1 mm of movement a one pulse signal is output to both output terminals A and B.

Furthermore, the maximum response speed of the sensor for the stroke reading cylinder is at a maximum cylinder speed of 1500 mm/s (15 kcps).



Input/Output

The input/output of the stroke reading cylinder is performed by a ø7 shielded twisted pair wire from the sensor section plus a connector.



Output circuit of stroke reading cylinder

Signal

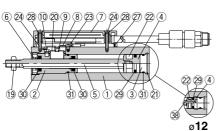
Contact signal	Wire color	Signal name
Α	White	A phase
В	Yellow	B phase
С	Brown	COM (0 V)
D	Blue	COM (0 V)
E	Red	+12 to 24 V
F	Black	0 V
G	—	Shield

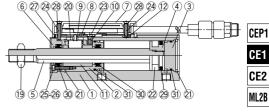
Auto Switch Proper Mounting Position

Regarding dimensions for the auto switch proper mounting position (at stroke end), refer to page 665.

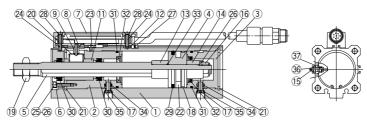
Construction

ø**12,** ø**20**





ø40 to ø63



ø**32**

Component Parts

No.	Description	Material	Note
1	Cylinder body	Aluminum alloy	
2	Rod cover	Brass	ø12 to ø20
2	Rod cover	Aluminum alloy	ø32 to ø63
3	Head cover	Aluminum alloy	
4	Piston	Aluminum alloy	
5	Piston rod	Stainless steel	
6	Rod cover disk	Aluminum alloy	
7	Sensor unit	—	
8	Sensor setting bracket	Stainless steel	
9	Sensor setting piece assembly	-	ø20 to ø63
10	Pin	Stainless steel	ø12 to ø32
11	Sensor guide	Lead-bronze casted	ø32 to ø63
12	Case setting nut	Carbon steel	ø32 to ø63
13	Cushion ring A	Rolled steel	ø40 to ø63
14	Cushion ring B	Rolled steel	ø40 to ø63
15	Cushion valve	-	ø40 to ø63
16	Piston nut	Rolled steel	ø40 to ø63
17	Port joint	Stainless steel	ø40 to ø63
18	Wear ring	Resin	ø40 to ø63

Component Parts

001	iponent i uno		
No.	Description	Material	Note
19	Rod end nut	Carbon steel	
20	Sensor setting plate	Cold rolled special steel strip	
21	Type C retaining ring	Carbon steel	
22	Magnet	_	
23	Round head Phillips screw	Carbon steel wire	
24	Cross recessed countersunk head screw	Carbon steel wire	
25	Hexagon socket head cap screw	Chromium molybdenum steel	
26	Spring washer	Steel wire	
27	Case gasket	NBR	
28	Case screw gasket	NBR	
29	Piston seal	NBR	
30	Rod seal	NBR	
31	Gasket	NBR	
32	Cushion seal	NBR	
33	Piston gasket	NBR	
34	Port seal	NBR	
35	Joint seal	NBR	
36	Valve seal	NBR	
37	Valve retainer seal	NBR	
38	Spacer for switch type	Aluminum alloy	ø12
	a de ana la a sa a albiliter af lasanas		and a CMC as a set line

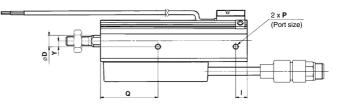
* Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

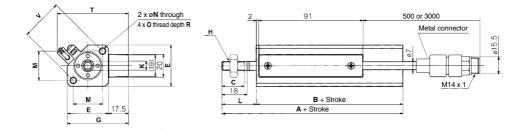


CE1 Series

Dimensions: ø12, ø20

	nds tapped			
CE1B	Bore size	-	Stroke	

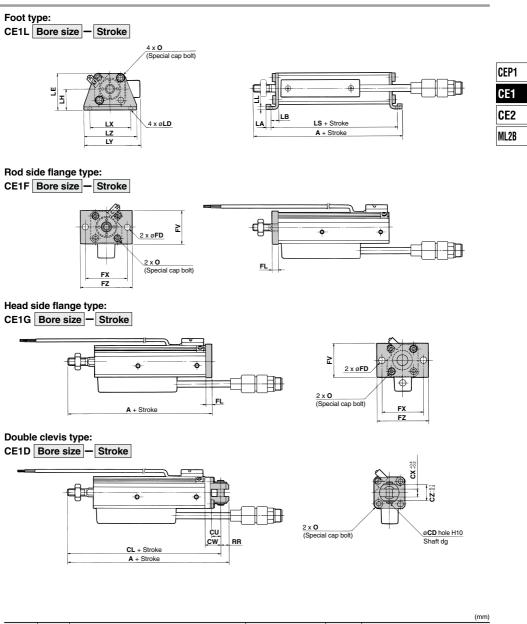




														(mm)
Bore size (mm)	St	andard stroke	A	В	С	D	E	G	н		1	к	L	М
12	25, 50	, 75, 100, 125, 150	93.5	69	15	6	25	42.5	M5 x 0.	в	16	5.2	24.5	15.5
20	25, 50, 75	5, 100, 125, 150, 175, 200	106	78	15.5	10	36	53.5	M8 x 1.2	5	10	8	28	25.5
Bore size (mm)	N	0		Р	Q	R	T *	v	Y					
12	—	M4 x 0.7	M5 :	x 0.8	47	7	53.5	22	7					
20	5.5	M6 x 1	M5 :	x 0.8	50	15	62.5	36	5					

SMC

* For rod end nut accessory bracket, refer to page 658. * Dimensions for auto switch model D-F79W.

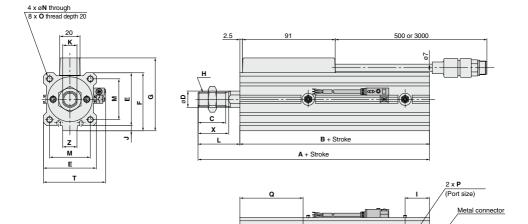


																										(11111)	
Bore size	Common		Foot type								Rod side flange, Head side flange Head side flange							e Double clevis type									
(mm)	0	Α	LA	LB	LD	LE	LH	LL	LS	LX	LY	LZ	FD	FL	FV	FX	FZ	Α	Α	CD	CL	CU	cw	СХ	cz	RR	
12	M4 x 0.7	106	4.5	8	4.5	29.5	17	2	85	34	52	44	4.5	5.5	25	45	55	99	113.5	5	107.5	7	14	5	10	6	D-🗆
20	M6 x 1	121	5.8	9.2	6.6	42	24	3.2	96.4	48	66.5	62	6.6	8	39	48	60	114	133	8	124	12	18	8	16	9	
																											-X□

CE1 Series

Dimensions: ø32, ø40, ø50, ø63

Both ends tapped type: CE1B Bore size - Stroke



1

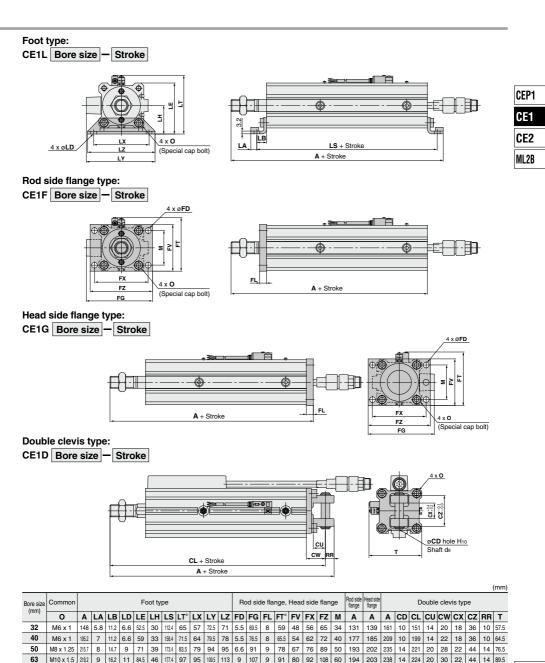
¢

۲

(mm)

Bore size (mm)	Sta	ndard stro	oke	Α	В	С	D	Е	F	G	ł	4	I	J	к
32	50, 75, 100,	50, 75, 100, 125, 150, 175, 200, 250, 300		131	90	27	16	45	49.5	64	M14	x 1.5	14	4.5	14
40	100, 125, 150, 175, 200, 250, 300, 400, 500		177	136	27	16	52	57	71.5	M14 x 1.5		24	5	14	
50	20	0, 300, 50	00	193	144	32	20	64	71	85.5	M18	M18 x 1.5		7	18
63	20	0, 300, 50	00	194	145	32	20	77	84	98.5	M18	x 1.5	21	7	18
Bore size (mm)	L	M	N		0		Р	Q	T *	Х	Z				
32	41	34	5.5	M	5 x 1	Rc	1/8	56	57.5	30	14				
40	41	40	5.5	M	6 x 1	5x1 Rc 1/8		62	64.5	30	14				
50	49	50	6.6	M8	x 1.25	Rc	1/4	61.5	76.5	35	19				
63	49	60	9	M10) x 1.5	Rc	1⁄4	64	89.5	35	19				

* For rod end nut accessory bracket, refer to page 658. * Dimensions for auto switch model D-F79W.



D-□ -x□

CE1 Series Auto Switch Mounting

Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

D-A9□ D-M9□	D-A9⊟V D-M9⊟V
D-M9⊟W	D-M9□WV
D-M9□A	D-M9□AV

ø12 to ø20

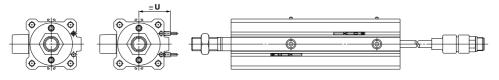


ø32 to ø63

D-A9□	
D-M9□	
D-M9⊡W	
D-M9□A	

D-A9⊔V	
D-M9⊡V	
D-M9⊟WV	
D-M9□AV	

. . .

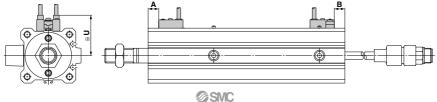


D-A7 □	D-F7NT
D-A80	D-F7BA
D-A7⊟H	D-A73C
D-A80H	D-A80C
D-F7□	D-J79C
D-J79	D-A79W
D-F7⊡W	D-F7⊟WV
D-J79W	D-J7⊡V
D-F79F	D-F7BAV

ø12 to ø20



ø32 to ø63



Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

Auto Swite	ch Prope	er Moun	ting Pos	ition								(mm)	
Auto switch model	D-A D-A		D-M9			473 480	D-A72/A7 D-A73C/A D-F79F/J D-J79C/F D-J79W/F	80C/F7 79/F7□V 7□W 7□W	D-F	7NT	D-A	79W	0504
Bore size		D-M9⊡AV		AV			D-F7BAV/F7BA						CEP1
(mm)	A	В	A	В	A	В	A	В	Α	В	Α	В	
12	37	5.5	41	9.5	38	6.5	38.5	7	43.5	12	35.5	4.5	CE1
20	46	12	50	16	47	13	47.5	13.5	52.5	18.5	44.5	10.5	
32	54	16	58	20	55	17	55	17.5	60.5	22.5	52.5	14.5	CE2
40	78	38	82	42	79	39	79.5	39.5	84.5	44.5	76.5	36.5	ULZ
50	81	43	85	47	82	44	82.5	44.5	87.5	49.5	79.5	41.5	MLOD
63	84.5	40.5	88.5	44.5	85.5	41.5	86	42	91	47	83	39	ML2B

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Auto Switch Mounting Height

Auto Swite	h Mounting	Height						(mm)
Auto switch model Bore size		D-M9⊡V D-M9⊡WV D-M9⊡AV	D-A7⊡ D-A80	D-A7 - H D-A80H D-F7 - D-J79 D-F7 - W D-F7 - W D-F7BA D-F79F D-F7NT	D-A73C D-A80C	D-F7⊡V D-F7⊡WV D-F7BAV	D-J79C	D-A79W
(mm)	U	U	U	U	U	U	U	U
12	20.5	20.5	19.5	20.5	26.5	23	26	22
20	25.5	25.5	24.5	25.5	31.5	28	31	27
32	27	29	31.5	32.5	38.5	35	38	34
40	30.5	32.5	35	36	42	38.5	41.5	37.5
50	36.5	38.5	41	42	48	44.5	47.5	43.5
63	40	42	47.5	48.5	54.5	51	54	50

* Auto switch mounting brackets BQ2-012 are not used for sizes over ø32 of D-A9 U/M9 U/M9 WV/M9 AVL types. In that case, the above values indicate the operating range when mounted with the current auto switch installation groove.

Minimum Auto Switch Mounting Stroke

No. of auto switches mounted	D-M9⊡V D-F7⊡V D-J79C	D-A9□V D-A7□ D-A80 D-A73C D-A80C	D-A9□	D-M9□WV D-M9□AV D-F7□WV D-F7BAVL	D-M9□ D-F7□ D-J79	D-M9⊡W D-M9⊡A	D-A7⊡H D-A80H	D-A79W	(mm D-F7⊡W D-J79W D-F7BA D-F79F D-F7NT
1 pc.	5	5	10 (5)	10	15 (5)	15 (10)	15 (5)	15	20 (10)
2 pcs.	5	10	10	15	15 (5)	15	15 (10)	20	20 (15)

ions stated in () shows the minimum stroke for the auto switch mounting when the auto switch does not project from the end surface of the cylinder body and hinder the lead wire bending space. (Refer to the figure below.) Note) The dim Order auto switches and auto switch mounting brackets separately



Operating Range

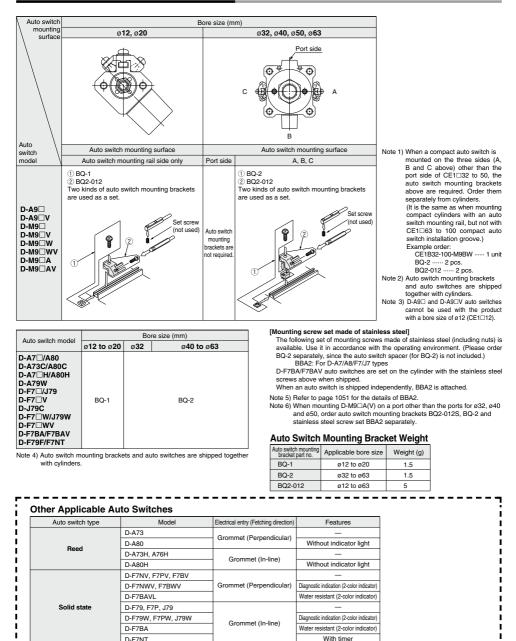
						(mm)			
Auto switch model	Bore size (mm)								
Auto switch model	12	20	32	40	50	63			
D-A9□(V)	7	9	9.5	9.5	9.5	11.5			
D-M9□(V) D-M9□W(V) D-M9□A(V)	2.5	4	6	6	6	6.5			
D-A7□(H)(C) D-A80□(H)(C)	9.5	12	12	11	10	12			
D-A79W	11.5	13	13	14	14	16			
D-F7□(V) D-J79(C) D-F7□W(V) D-F7BA(V) D-F7NT D-F79F	4	5.5	6	6	6	6.5			

* Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.



CE1 Series

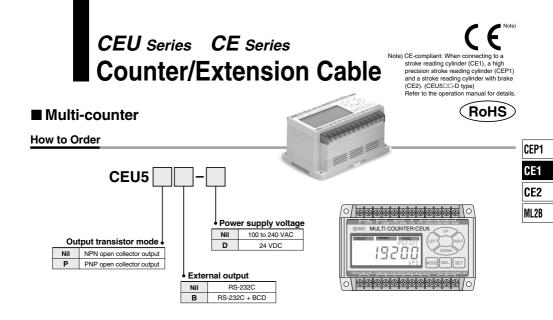
Auto Switch Mounting Bracket: Part No.



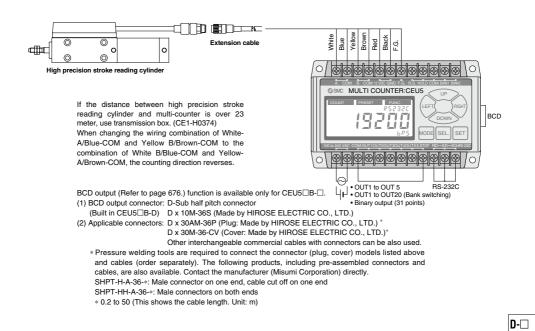
* For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1014 and 1015 for details.
* Normally closed (NC = b contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 959.



I



Connection Method



@SMC

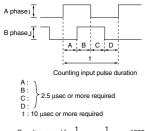
-X□

CEU Series

Multi-counter/Specifications

Model	CEU5	CEU5-D	CEU5P	CEU5P-D	CEU5B	CEU5B-D	CEU5PB	CEU5PB-D				
Туре				Multi-c	ounter							
Mounting			Sur	face mounting (D	IN rail or Screw s	stop)						
Operating system				Adding - sub	tracting type							
Operation mode			Operating m	ode, Data setting	mode, Function	setting mode						
Reset system				External res	set terminal							
Display system				LCD (With	back light)							
Number of digits				6 di	gits							
Memory holding {Storage medium}	Setting value (all	ways held), Count	value (Hold/Non-	hold switching), {E	E ² ROM (Warning	display after writin	ig approx. 800,00	0 times: E2FUL)}				
Input signal type			Count input, C	Control signal inpu	ut (Reset, Hold, E	Bank selection)						
Count input				No-voltage	pulse input							
Pulse signal system		90° phase difference input *1/ UP/DOWN separate input *2										
Counting speed				100 k	Hz *1							
Control signal input				Voltage input (12	VDC or 24 VDC)						
Sensor power supply				10.8 to 13.2	VDC, 60 mA							
Output signal type	Р	reset output, Cyli	nder stop output	t	Preset o	output, Cylinder st	top output, BCD	output				
Preset output configuration			Comp	are/Hold/One-sh	ot (100 ms fixed	pulse)						
Output type			Sepa	arate 5 point outp	ut/Binary code o	utput						
Output delay time			5 ms or less (for normal output)/60 ms or less (Binary output)						
Communication system				RS-2	232C							
Output transistor mode	NPN oper Max 30 VE			n collector DC, 50 mA	NPN oper Max 30 VD0			n collector C, 50 mA * ³				
Power supply voltage	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC				
Power consumption	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less				
Withstand voltage				en case and AC li en case and signa								
Insulation resistance		Between	case and AC lin	ne: 50 M Ω or more	e (500 VDC mea	sured via megoh	mmeter)					
Ambient temperature				0 to +50°C (No freezing)							
Ambient humidity				35 to 85% RH (N	lo condensation)							
Noise resistance	Square wa	ve noise from a r	ioise simulator (pulse duration 1 µ	ıs) between pow	er supply termina	als ±2000 V, I/O	line ±600 V				
Shock resistance		E	ndurance 10 to	55 Hz; Amplitude	0.75 mm; X, Y,	Z for 2 hours eac	h					
Impact resistance			Endura	nce 10 G; X, Y, Z	directions, 3 tim	es each						
Weight				350 g (or less							

*1) 90° phase difference input

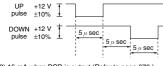


Counting speed f =
$$\frac{1}{t} = \frac{1}{10 \times 10^{-6}} = 10000 \text{ Hz}$$

 $\approx 100 \text{ kHz}$

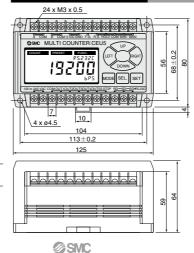
* 2) UP/DOWN input

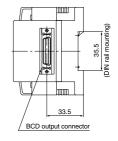
Input wave form conditions: At a maximum of 100 kHz, the UP/DOWN wave form should be as shown below.



* 3) 15 mA when BCD is output (Refer to page 676.)

Multi-counter/Dimensions





Counter CEU Series

Wiring with External Equipment

<Wiring with multi-counter CEU5>

1. Wiring of power source for driving counter For power source for driving counter, use the one with 90 to 264 VAC, 50/60 Hz or 21.6 to 26.4 VDC, 0.4 A or more.

2. Wiring for control signal input

(Selection among Reset, Hold, Bank (Refer to page 676.)) Make each control signal to be the transistor which can run more than 15 mA or the contact output. Input time for reset signal should be more than 10 ms. Bank (Refer to page 676.) selection and hold will function only when the input signal is applied.

COM is common to each signal input. Applicable to NPN and PNP input. Use 24 VDC or 12 VDC for the power source of COM. Connect DCwhen PNP is applied, and DC+ when NPN is applied.

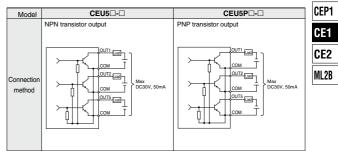




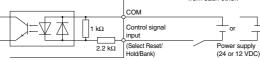
3. Output circuit

There are two outputs, the NPN open collector and the PNP open collector. The maximum rating is 30 VDC, 50 mA. Operating the controller by exceeding this voltage and amperage could damage the electric circuit.

Therefore, the equipment to be connected must be below this rating.

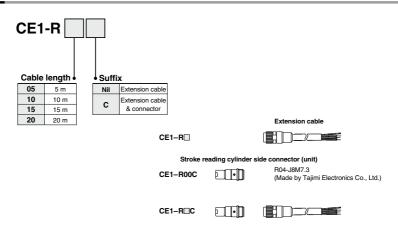


* However, the COM of the input circuit and the COM of the output circuit are electrically insulated from each other.



Extension Cable

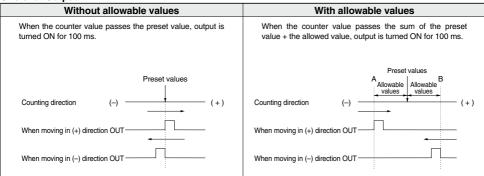
How to Order



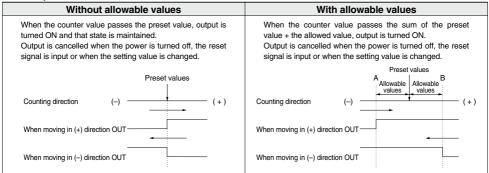
CEU Series

Operating Condition of each Output Mode

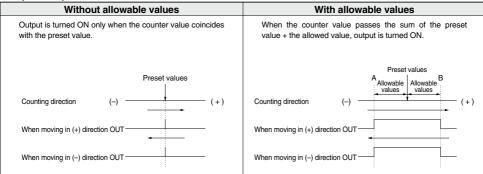
One-shot Output



Hold Output

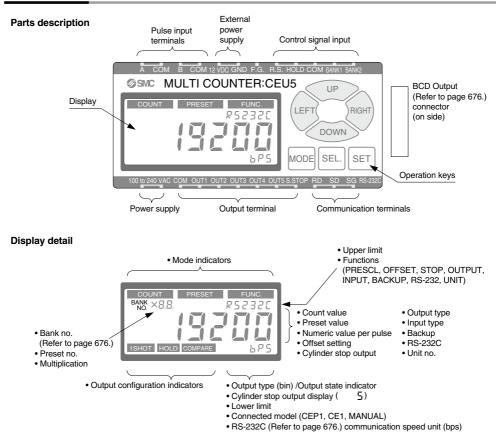


Compare Output



CEU Series

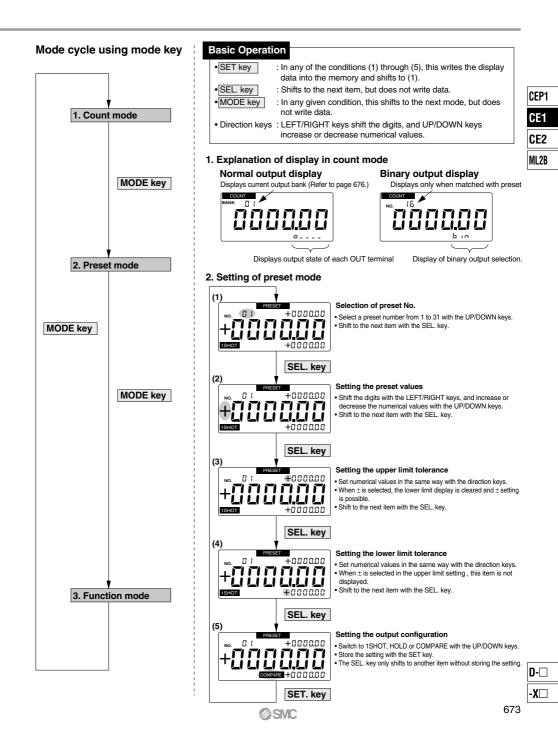
CEU5 Operation



Key and Functions

Key	Functions
MODE	Changes the mode. In any given condition, it shifts to the next mode. Does not write data.
SEL.	Shifts the cursor to the next item. Does not write data.
SET	Writes displayed data into the memory when setting.
RIGHT	Shifts the cursor to the right when setting numerical values.
LEFT	Shifts the cursor to the left when setting numerical values.
UP	Changes the contents of a setting. Increases the value when setting numerical values.
DOWN	Changes the contents of a setting. Decreases the value when setting numerical values.

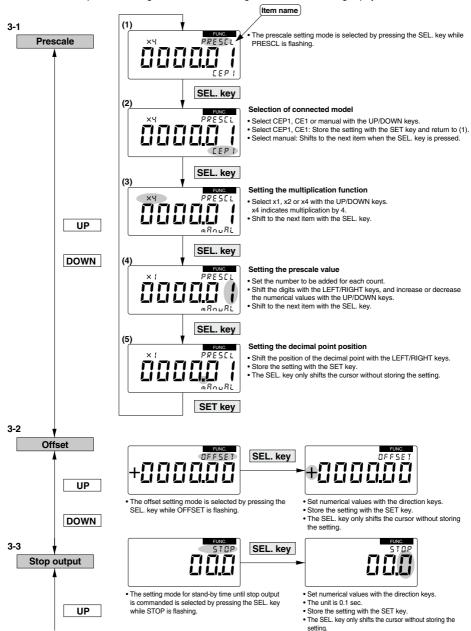
In the explanations of the operating method, references to "Direction keys" indicate the 4 keys RIGHT, LEFT, UP and DOWN.



CEU5 Operation

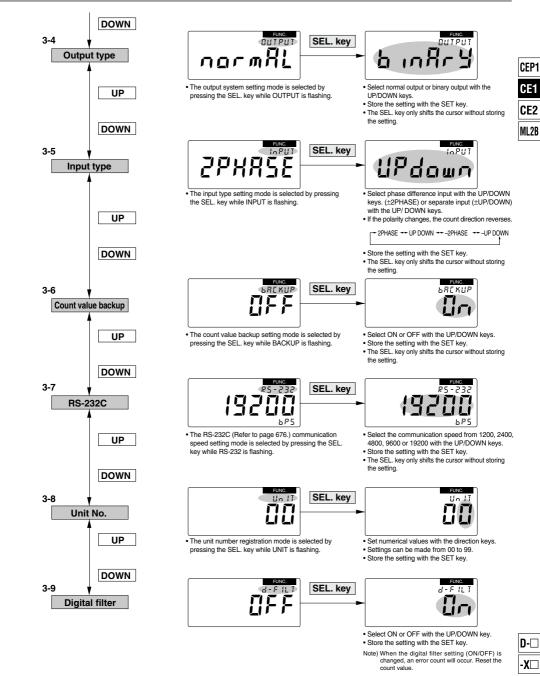
3. Explanation of settings in the function mode

If the UP/DOWN keys are pressed when an item name is flashing, it shifts to another setting item. When the SEL key is pressed, the cursor shifts and it is possible to change the content of the setting for the item which is being displayed.



@SMC





CEU Series Glossary (Functions of CEU5)

BCD Output

This is a system which expresses one digit of a decimal number with a 4 digit binary number.

The count value is expressed by the ON/OFF state of each BCD output terminal. In the case of 6 digits, 24 terminals are required.

The relation between decimal numbers and BCD codes is shown in the table below.

Decimal no.	0	1	2	3	4	5	6	7	8	9
BCD	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001

Ex.) 1294.53 is expressed as follows.

0001 0010 1001 0100 0101 0011

RS-232C

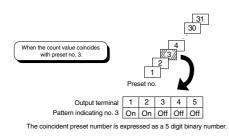
This is the interface standard for the serial transmission method, which is standard equipment on a personal computer.

Prescale Function

This function allows free setting of how many millimeters will indicate one pulse.

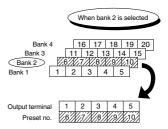
Binary Output

31 point preset output is possible without bank switching, by means of binary system output from a 5 point output terminal. Cylinder stop output is used as the readout release signal.



Bank Function

5 points of preset output are possible simultaneously, however, a maximum of 20 types of work discrimination, etc. can be performed by using the 5 points of preset values as one of a maximum of four quadrats, and switching its use during operation.



For example, when bank 2 is selected, presets 6 through 10 are valid and when the count value coincides with the setting value of 6 through 10, the respective output terminals 1 through 5 are turned ON.

Bank Switching Correspondence

Input terminal Bank no.	BANK2	BANK1
1	OFF	OFF
2	OFF	ON
3	ON	OFF
4	ON	ON

CEP1

CE1

CE2

ML2B

Display Offset Function

Normally the count value returns to "0" after resetting, but with this function, the initial value can be set to any desired value.

Hold Function

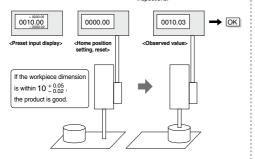
When "hold" is input, the counter holds the current count value in memory. Next, when the count value is read into a PLC which uses serial or BCD output, etc., the count value that was held can be read in, even if there is a time lag.

Setting the Tolerances of Preset Values

The tolerance can be set as $+ \bigcirc$ mm and $- \blacktriangle$ mm. Additionally, the setting of $+ \bigcirc$ mm and $+ \triangle$ mm, or $- \clubsuit$ mm and $- \blacktriangle$ mm is also possible. (However, $\bigcirc > \triangle$ and $\bigstar > \clubsuit$ should be satisfied.)

By including preset tolerance setting, superior performance is exhibited in parts inspections, etc. In a workpiece to be measured, there are tolerances which assure a good product. For example, in the case of $10^{+0.05}_{-0.02}$, the CEU5 allows these tolerances to be input as they stand. If the workpiece is within tolerances the OK signal is sent.

<Simple input as per drawing dimensions> Tolerances can be set with the preset value. OK/NG signal is output by the counter. Labor savings can be realized in parts inspections.



Count Value Protection

In the past, the count value returned to "0" when the power supply was cut off, but this function holds the previous value even after a power failure. This function can be switched between active and inactive settings.

Cylinder Stop Output

When workpiece discrimination is performed using a preset counter, it has been common to estimate the amount of time from the cylinder's start of operation until it touches the workpiece and stops, using a timer to read the output after a fixed amount of time. Since cylinder stop output is now output when there is no cylinder movement for a fixed amount of time, timing of preset output and external output, etc. is simplified.

