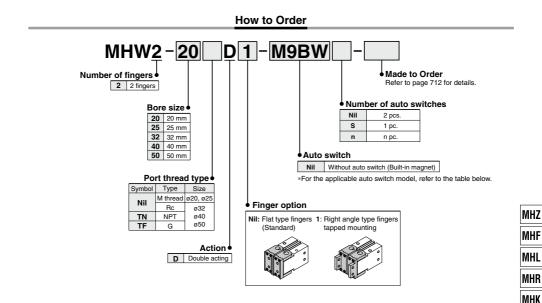
## 180° Angular Type Air Gripper Rack & Pinion Type MHW2 Series ø20, ø25, ø32, ø40, ø50



#### Applicable Auto Switches / Refer to pages 797 to 850 for further information on auto switches

							Load voltage				Load voltage		Load voltage		Load voltago		Auto		ch model	Ŀ	ead wire I	ength (m)	1*			
Туре	Special function					Wiring (Output)		Loau voitay			0.5	1	3	5	Pre-wired connector		cable									
	Turicuon	Chury	iigin	(Output)		DC	AC	Perpendicular	In-line	(Nil)	(M)	(L)	(Z)	connector	10	load										
				3-wire(NPN)		5 V. 12 V		M9NV	M9N	۲	•	•	0	0	IC											
5 C				3-wire(PNP)		5 V, 12 V		M9PV	M9P	۲	•	•	0	0	circuit											
switch				2-wire	12 V				M9BV	M9B	•	•	•	0	0	_										
auto :	Diagnosis			3-wire(NPN)				EV 1	EV 10 V	EV 10 V	5 V 12 V	5 V. 12 V		M9NWV	M9NW	۲	•	•	0	0	IC					
		Grommet	Yes	3-wire(PNP)	24 V	5 V, 12 V	-	M9PWV	M9PW	۲	•	•	0	0	circuit	Relay, PLC										
state	indicator)			2-wire		12 V		M9BWV	M9BW	٠	•	•	0	0	_											
Solid :	Water			3-wire(NPN)		5 V, 12 V		M9NAV**	M9NA**	0	0	•	0	0	IC											
So	resistant (2-color			3-wire(PNP)		5 V, 12 V		M9PAV**	M9PA**	0	0	•	0	0	circuit											
	indicator)			2-wire		12 V		M9BAV**	M9BA**	0	0	•	0	0	_											

\*\* Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance. \* Lead wire length symbols: 0.5 m ...... Nil (Example) M9NW \* Auto switches marked with a "O" symbol are produced upon receipt of order.

- 1 m ······· M (Example) M9NWM

  - 3 m ······· L (Example) M9NWL 5 m ······ Z (Example) M9NWZ

Note 1) When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the

air gripper. Note 2) When ordering the air gripper with the auto switch, the auto switch mounting bracket is included.

When ordering the auto switch separately, the auto switch mounting bracket (BMG2-012) is required.

@SMC

MHS

MHC МНТ MHY MHW -X□ MRHO

MA

D-🗆



#### Specifications

Fluid	Air
Operating pressure	0.15 to 0.7 MPa
Ambient and fluid temperature	-10 to 60°C
Repeatability	±0.2 mm
Max. operating frequency	ø20, 25: 60 c.p.m.
Max. operating nequency	ø32 to 50: 30 c.p.m.
Lubrication	Not required
Action	Double acting
Auto switch (Option) Note)	Solid state auto switch (3-wire, 2-wire)

Note) Refer to pages 797 to 850 for further information on auto switches.

#### Symbol

Double acting: External grip



0,00	Made to Order						
	(Refer to pages 725 to 748 for the details.)						
Symbol	Specifications/Description						
-X4	Heat resistance						
-X5	Fluororubber seal						
-X50	Without magnet						
-X53	EPDM for seals, Fluorine grease						
-X63	Fluorine grease						
-X79	Grease for food processing machines, Fluorine grease						
-X79A	Grease for food processing machines						

#### Model

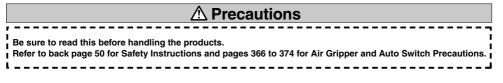
Model	Bore size (mm)	Effective gripping force (N·m)	Openin (Both Opening	Weight (2) (g)	
MHW2-20D	00	0.30		-5°	300
MHW2-20D1	20	0.30		-9	320
MHW2-25D	05	0.73	180°	-6°	510
MHW2-25D1	25	0.73			540
MHW2-32D	00	1.61			910
MHW2-32D1	32	1.01			950
MHW2-40D	40	3.70		-5°	2140
MHW2-40D1	40	3.70			2270
MHW2-50D	50	8.27			5100
MHW2-50D1	50	0.27		-4	5350

Note 1) At the pressure of 0.5 MPa

Note 2) Except auto switch

• Refer to "How to Select the Applicable Model" on page 700

• Refer to pages 700 and 701 for the details on effective holding force and allowable overhanging distance.

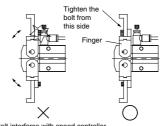


#### Mounting

#### MHW

### **▲** Warning

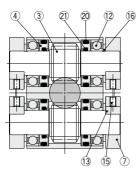
When using right angle finger tap mounting type, monitor the interference of the bolt with the speed controller.

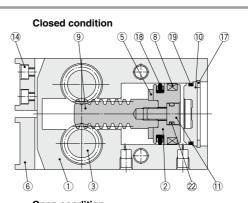


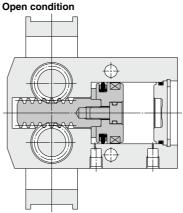
Bolt interferes with speed controller



#### Construction







#### **Component Parts**

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Piston	Aluminum alloy	Hard anodized
3	Pinion gear	Carbon steel	Heat treated
4	Seal cover	Brass	
5	Bumper	Urethane rubber	
6	Finger (A)	Carbon steel	Nitriding
7	Finger (B)	Carbon steel	Nitriding
8	Rubber magnet	Synthetic rubber	
9	Rack	Carbon steel	Nitriding

No.	Description	Material	Note
10	Can	ø20, 25: Resin	
10	Сар	ø32 to 50: Aluminum alloy	Hard anodized
11	Piston bolt	Stainless steel	
12	Ball bearing	Carbon steel	Schield type
13	Key	Carbon steel	
14	Hexagon socket head bolt	Carbon steel	Zinc chromated
15	Hexagon socket cap screw	Carbon steel	Zinc chromated
16	Type C retaining ring	Carbon steel	Phosphate coated
17	Type C retaining ring	Carbon steel	Phosphate coated

#### **Replacement Parts**

Description		MHW2-20	MHW2-25	MHW2-32	MHW2-40	MHW2-50	Main parts
Seal kit		MHW20-PS	MHW25-PS	MHW32-PS	MHW40-PS	MHW50-PS	1819202122
Piston assembly		MHW-A2001	MHW-A2501	MHW-A3201	MHW-A4001	MHW-A5001	25891122
Finger cocombly	MHW2-□D	MHW-A2002	MHW-A2502	MHW-A3202	MHW-A4002	MHW-A5002	(6)(7)(13(14(15)
Finger assembly	MHW2-DD1	MHW-A2002-1	MHW-A2502-1	MHW-A3202-1	MHW-A4002-1	MHW-A5002-1	000000
Finger A assembly	MHW2-□D	MHW-A2006	MHW-A2506	MHW-A3206	MHW-A4006	MHW-A5006	614
Finger C assembly	MHW2-DD1	MHW-A2006-1	MHW-A2506-1	MHW-A3206-1	MHW-A4006-1	MHW-A5006-1	614
Finger B assembly		MHW-A2007	MHW-A2507	MHW-A3207	MHW-A4007	MHW-A5007	71315

\* Please order 1 piece finger assembly per one unit.

Replacement part/grease pack part no. : ø20, ø25, ø32 : GR-S-010(10 g)

ø40, 50 : GR-S-020(20 g)

MHZ MHF MHL

MHR

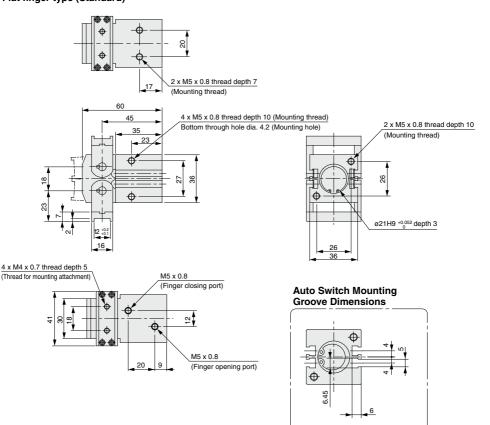
MHK MHS MHC

MHT MHY MHW -X🗆 MRHQ MA

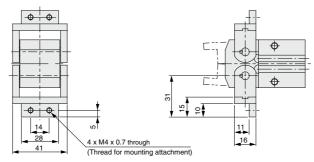
D-🗆

#### Dimensions

#### MHW2-20D Flat finger type (Standard)



#### MHW2-20D1 Right angle finger type



#### Dimensions

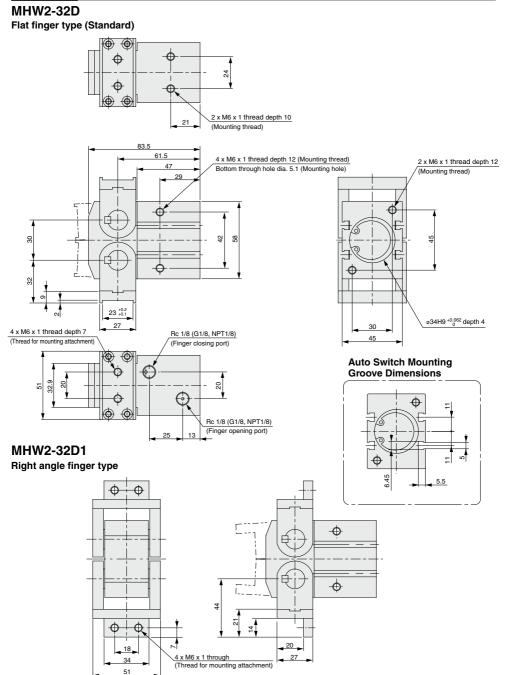
#### **MHW2-25D** Flat finger type (Standard) ⊕⊕ Ð 24 Ð ۲ 6 2 x M6 x 1 thread depth 10 20 (Mounting thread) 4 x M6 x 1 thread depth 12 (Mounting thread) 69 2 x M6 x 1 thread depth 12 51 Bottom through hole dia. 5.1 (Mounting hole) (Mounting thread) 40 2 55 24 34 8 Œ 27 17<sup>+0.3</sup> ø26H9 +0.052 depth 3 MHZ 30 21 40 MHF 4 x M5 x 0.8 thread depth 6 M5 x 0.8 (Thread for mounting attachment) (Finger closing port) Auto Switch Mounting Groove Dimensions MHL 1 MHR \$ 16 S MHK Ð ⊕€ MHS 23 10 M5 x 0.8 (Finger opening port) MHC 4.5 MHT MHW2-25D1 6.45 5.5 Right angle finger type MHY MHW φ Φ -X🗆 MRHQ $\Phi$ MA D-🗆 $\oplus$ 37 ¢ æ <u>م</u> ŝ 16 15 4 x M5 x 0.8 through 30 21



(Thread for mounting attachment)

45

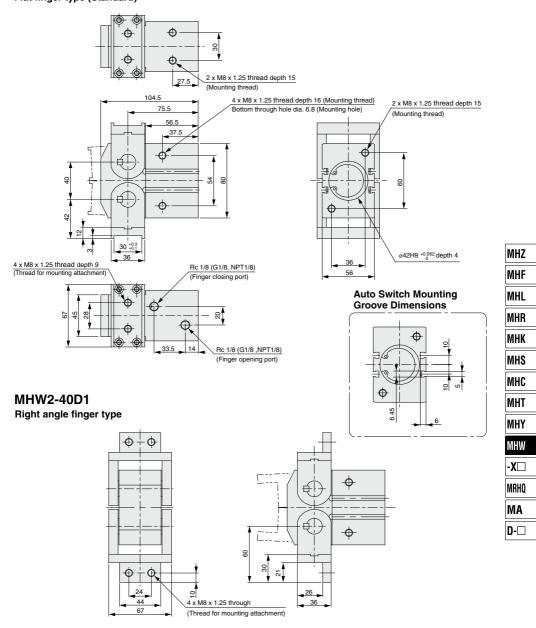
#### Dimensions



**SMC** 

#### Dimensions

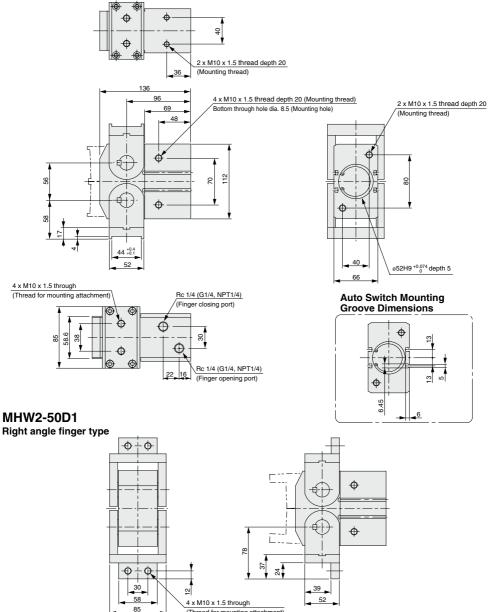
#### MHW2-40D Flat finger type (Standard)



#### Dimensions

#### MHW2-50D

Flat finger type (Standard)



(Thread for mounting attachment)



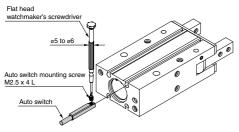
## MHY2/MHW2 Series **Auto Switch Installation Examples** and Mounting Positions

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions. **Detection when Gripping Exterior of Workpiece** 

Detection example	1. Confirmation of the fingers in reset position	2. Confirmation of work held	
	Position of fingers fully opened	Position when gripping a workpiece	
Position to be detected			
Operation of auto switch	Auto Switch turned ON when fingers return. (Light ON)	Auto Switch turned ON when gripping a workpiece. (Light ON)	
How to determine auto switch installation position	Step 1) Completely open the fingers.	Step 1) Position fingers for gripping a workpiece.	MHZ
At no pressure or low pressure, connect the auto switch to a	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing.	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing.	MHF
power supply, and follow the directions.			MHL
			MHR
	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. Move the	MHK
		switch an additional 0.3 to 0.5 mm in the direction of the arrow and fasten it.	MHC
			MHT
	Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out.	Position where light turns ON	MHY
			MHW -X□
	Step 5) Move the auto switch in the opposite direction	Position to be secured	MRHQ
	and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates.		MA
	Position where light turns ON Position to be secured	⊕(⊕-+է♥	<b>D</b> -□

#### **Auto Switch Mounting**

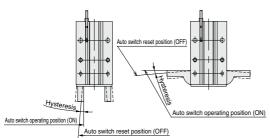
To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.



- Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw. The tightening torque should be about 0.05 to 0.15 N·m.
- \* Refer to the page 804 for the details on "Auto Switches Connection and Example".

#### Auto Switch Hysteresis

Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.



		D-M9□(V) D-M9□W(V)/M9A(V)
MHY2	Finger fully closed	2°
-10D	Finger fully open	<b>4</b> °
MHY2	Finger fully closed	2°
-16D	Finger fully open	3°
MHY2	Finger fully closed	2°
-20D	Finger fully open	3°
MHY2	Finger fully closed	1°
-25D	Finger fully open	2°

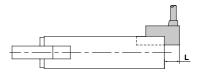
#### Protrusion of Auto Switch from Edge of Body

The projection of an auto switch from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

Note) 2-color indicator type and perpendicular entry type protrude in the direction of the lead wire entry.



When auto switch D-M9 is used



When auto switch D-M9 V is used

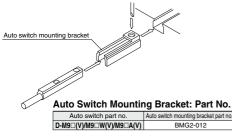
#### Max. Protrusion of Auto Switch from Edge of Body (L)

Auto	switch	Protrusion					
$  \setminus \setminus$	model		Perpendicular	In-line	Perpendicular		
Air gripper model	nger isition	D-M9⊡ D-M9⊡W	D-M9⊡V D-M9⊡WV	D-M9⊡A	D-M9⊡AV		
MHY2-10D	Open	-	—	—	—		
WITT2-10D	Closed	3	1	5	3		
MHY2-16D	Open	-	-	—	-		
WIN 12-10D	Closed	3	1	5	3		
MHY2-20D	Open	_	_	_	_		
WITT 2-20D	Closed	—	—	3	1		
MHY2-25D	Open	—	—	—	—		
WITT 2-25D	Closed	—	—	1	—		

(mm)

#### Auto Switch Mounting

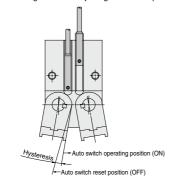
- (1) Insert the auto switch bracket into the installation groove of the gripper as shown below and roughly set it.
- (2) Insert the auto switch into the auto switch bracket installation groove.
- (3) After confirming the detecting position, tighten the set screws (M2.5) attached to the auto switch and set it.
- (4) Be sure to change the detecting position in the state of (2).



Note) Use a screwdriver with a grip diameter of 5 to 6 mm to tighten the set screws (M2.5). The tightening torque should be 0.5 to 1 N-m. As a rule, it should be turned about 90° beyond the point at which tightening can be felt.

#### Auto Switch Hysteresis

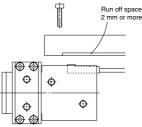
Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.



Auto switch Air gripper model model	D-Y59□/Y69□ D-Y7P(V)/Y7□W(V)
MHW2-20D	4°
MHW2-25D	4°
MHW2-32D	2°
MHW2-40D	2°
MHW2-50D	2°
s	
Auto switch	Max. hysteresis (Max. value)
model	D-M9□(V)
Air gripper	D-M9□W(V)
model	D-M9□A(V)
MHW2-20D	4°
MHW2-25D	4°
MHW2-32D	2°
MHW2-40D	2°
MHW2-50D	2°

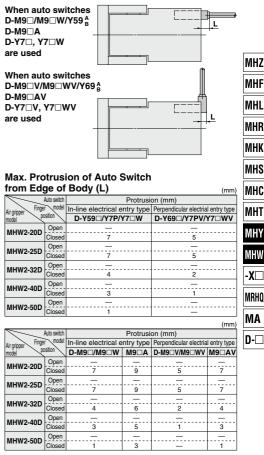
#### Handling of Mounting Brackets

When auto switch is set on mounting side as shown below, allow at least 2 mm run off space on mounting late since the auto switch is protruded from the gripper edge.



#### Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully closed) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.



MHF MHI MHR MHK MHS MHC MHT MHY MHW -X□ MRHO MA D-



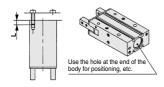
# MHY2/MHW2 Series Specific Product Precautions 1

Be sure to read this before handling the products.

#### Mounting Air Grippers/MHY2 Series

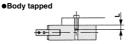
Possible to mount from 3 directions.

#### Axial Mounting (Body Tapped)



Model			ightening e (N⋅m)	Max. screw-in depth (Lmm)	
MHY2-10D	M3 x 0.5	0	.88	6	
MHY2-16D	M4 x 0.7	2	2.1	8	
MHY2-20D	M5 x 0.8	4.3		10	
MHY2-25D	M6 x 1	7.4		12	
Model	Bore(mr	n) Hole de		epth (mm)	
MHY2-10D	Y2-10D Ø11H9 *			1.5	
MHY2-16D	ø17H9 *	0.043		1.5	
MHV2-20D	a21H9 +9	0.052	1.5		

Lateral mounting (Body Tapped, Body through-hole)

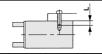


Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.88	6
MHY2-16D	M4 x 0.7	2.1	8
MHY2-20D	M5 x 0.8	4.3	10
MHY2-25D	M6 x 1	7.4	12

#### Body through-hole

Model	Applicable bolts	Max. tightening torque (N·m)
MHY2-10D	M3 x 0.5	0.88
MHY2-16D	M4 x 0.7	2.1
MHY2-20D	M5 x 0.8	4.3
MHY2-25D	M6 x 1	7.4

Vertical Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.59	4
MHY2-16D	M4 x 0.7	1.3	5
MHY2-20D	M5 x 0.8	3.3	8
MHY2-25D	M6 x 1	5.9	10

How to Mount the Attachment to the Finger



(1) To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.

(2) Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Model	Applicable bolts	Max. tightening torque (N·m)
MHY2-10D MHY2-16D	M3 x 0.5	0.59
MHY2-20D	M4 x 0.7	1.4
MHY2-25D	M5 x 0.8	2.8

#### **Operating Environment/ MHY2 Series**

## **A**Caution

MHY2-25D Ø26H9 \*

#### Use caution for the anti-corrosiveness of finger guide section.

Martensitic stainless steel is used for the finger. However, be aware that its anti-corrosion performance is inferior to austenitic stainless steel. In particular, the finger might be rusted in an environment where water droplets are adhered to it due to dew condensation.



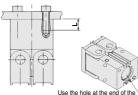
## MHY2/MHW2 Series Specific Product Precautions 2

Be sure to read this before handling the products.

#### Mounting Air Grippers/MHW2 Series

Possible to mount from 3 directions.

#### Axial Mounting (Body Tapped)



Use the hole at the end of th body for positioning, etc.

Model	Applicable bolts		ghtening e (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4	.3	10
MHW2-25D	M6 x 1	7	.4	12
MHW2-32D	M6 x 1	7	.4	12
MHW2-40D	M8 x 1.25	11	7.7	15
MHW2-50D	M10 x 1.5	3	7.2	20
Model	Bore(mr	n)	Hole d	lepth (mm)
Model MHW2-20D	Bore(mr ø21H9 *0	<i>'</i>	Hole d	lepth (mm)
		052	Hole d	
MHW2-20D	ø21H9 +8	052	Hole d	3
MHW2-20D MHW2-25D	ø21H9 +0. ø26H9 +0. ø34H9 +0. ø34H9 +0. ø42H9 +0.	052 052 062 062	Hole d	3 3
MHW2-20D MHW2-25D MHW2-32D	ø21H9 *0 ø26H9 *0 ø34H9 *0	052 052 062 062	Hole d	3 3 4

#### Lateral mounting (Body Tapped, Body through-hole)

#### Body tapped



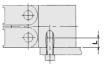
Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4.3	10
MHW2-25D	M6 x 1	7.4	12
MHW2-32D	M6 x 1	7.4	12
MHW2-40D	M8 x 1.25	17.7	16
MHW2-50D	M10 x 1.5	37.2	20

#### Body through-hole



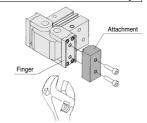
Model	Applicable bolts	Max. tightening torque (N·m)
MHW2-20D	M4 x 0.7	2.1
MHW2-25D	M5 x 0.8	4.3
MHW2-32D	M5 x 0.8	4.3
MHW2-40D	M6 x 1	7.4
MHW2-50D	M8 x 1.25	17.7

Vertical Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	2.9	7
MHW2-25D	M6 x 1	5.9	10
MHW2-32D	M6 x 1	5.9	10
MHW2-40D	M8 x 1.25	17.7	15
MHW2-50D	M10 x 1.5	37.2	20

#### How to Mount the Attachment to the Finger



 To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
 Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

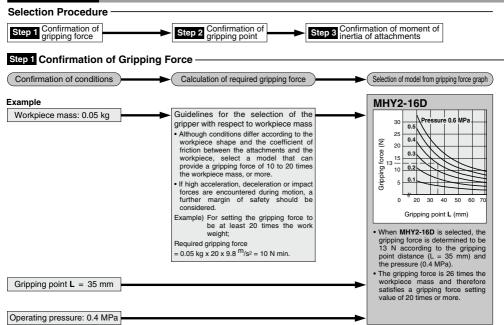
Applicable bolts	Max. tightening torque (N·m)
M4 x 0.7	1.4
M5 x 0.8	2.5
M6 x 1	4.1
M8 x 1.25	10.6
M10 x 1.5	24.5
	M4 x 0.7 M5 x 0.8 M6 x 1 M8 x 1.25

MHZ

MHF

# MHY2/MHW2 Series Model Selection

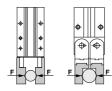
#### Model Selection

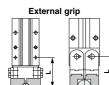


#### Effective Gripping Force-

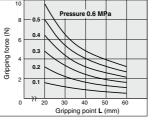
#### MHY2/MHW2 Series Double Acting

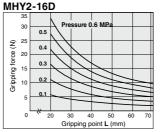
 Indication of effective gripping force The effective gripping force shown in the graphs to the right is expressed as F, which is the impellent force of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.



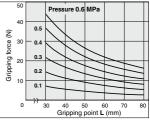


#### MHY2-10D

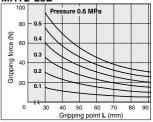


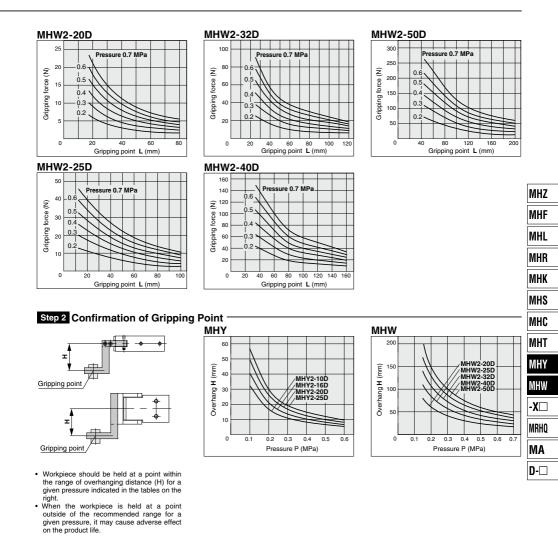


#### **MHY2-20D**



#### MHY2-25D





**SMC**